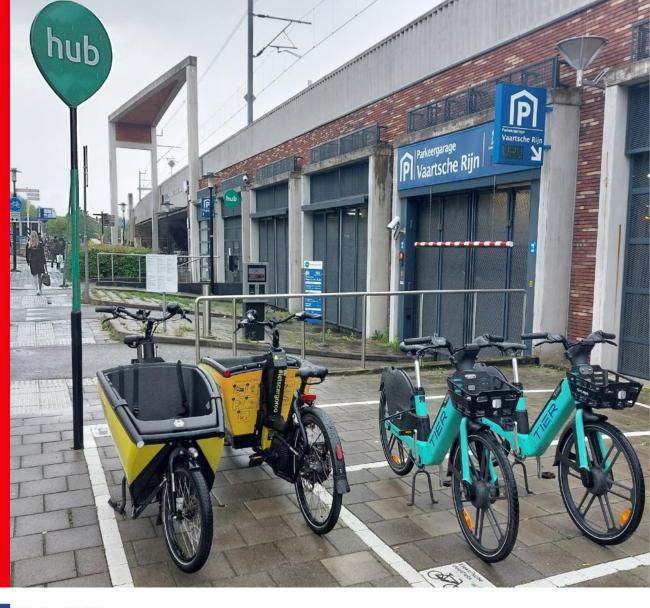
A GIS Approach for Identifying Suitable Locations for Shared Mobility Vehicles in Urban and Rural Areas of the Netherlands

19 Juni 2025 Gido Stoop















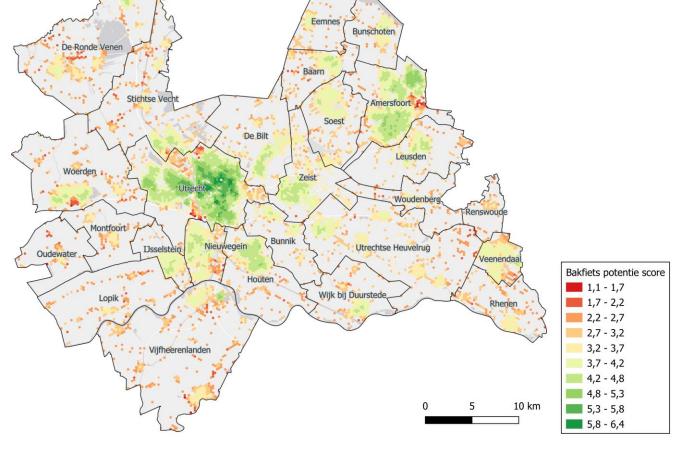
Why?

- Locations are selected on 'gut feeling'
- Lacking expertise on shared mobility in some municipalities
- Consultants are expensive and quality is varying



The research

- A method for finding the most suitable locations for shared vehicles
- Todays example: Shared Cargo Bikes









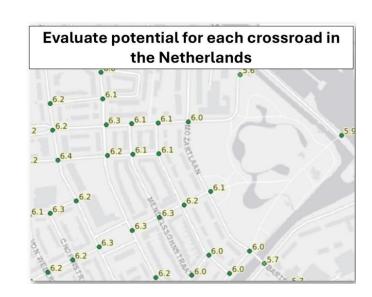
Knowledge from literature and workshops to criteria

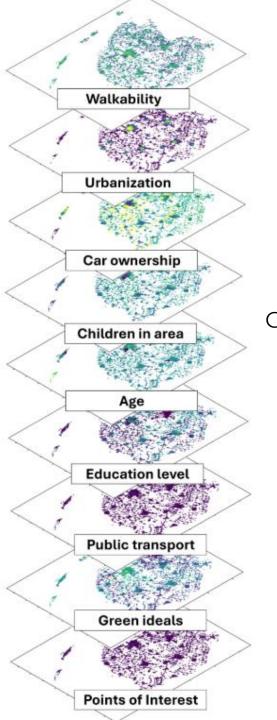
- Shared mobility is rather 'new'
- First, literature review
- Then workshops
 - Sticky note session
 - Municipalities, companies, public/private partners

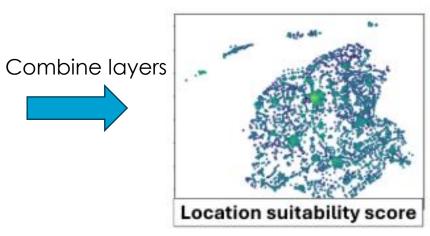


Indicators & Method

- Open datasets
- National level
- For every crossroad
- Combine for final score







Goals of the (practical) research

- Tracebale
- Reproducable
- Understandable
- Therefore:
 - Ipynb (python and Github)
 - Webmap
 - Physical prototype
 - Guidebook
 - Scientific paper

1.2 Load and Preprocess OSM Roads

- Load the road shapefile
- Remove minor road types
- Dissolve by name
- Convert MultiLineStrings to single lines
- X Line intersections: Find crossroads

```
def merge multilinestring(geometry):
    if isinstance(geometry, MultiLineString):
        merged = linemerge(geometry)
       return merged
    return geometry
area name = 'Prov Utrecht'
coord system = 28992
OSM_streets_file = fr"sources/osm_roads_{area_name}/gis_osm_roads_free 1.sh
output file = fr"output/crossroads/crossroads {area name} {coord system}.gg
# Download and open OSM roads
streets gdf = gpd.read file(OSM streets file)
streets gdf = streets gdf.to crs(epsg=28992)
# Remove small paths
rm path types list = ["bridleway", "busway", "footway", "motorway", "path",
streets filtered gdf = streets gdf[~streets gdf["fclass"].isin(rm path type
# Dissolve seperate parts of street to one
streets filtered gdf = streets filtered gdf.dissolve('name')
```

Indicator	Coefficient R ² = 0.50	P-value	Weights
Walkability	-7250	0.000	0.31
Urbanization	-22670	0.000	1.00
Car ownership	-7789	0.008	0.37
Children in area	1853	0.362	0.00
Age	-12170	0.000	0.56
Education level	-3755	0.006	0.18
Public transport	-3658	0.132	0.00
Green ideals	-4814	0.000	0.19
Points of interest	-4200	0.007	0.21
*In spatial models an $R^2 > 0.50$ is considered a good fit			





Validation & Calibration

- Free-floating user coordinates data from Rotterdam
- Dependent variable: Average distance to the 50 closest datapoints
- Weights are applied to the final score calculation

Drawbacks and How to use this?

- Real world is much more complex
- Every city and village is different
- For a first exploration of the area
- To get a grasp of the important criteria
- Data driven decision making
- As a starting point of dialog and discussion



Next steps

- Do the same for mopeds, bicycles and cars
- Combine models for a 'hub' model
- Finish paper
- Finish guidebook







ShareDiMobiHub

Questions?

Gido Stoop, Gidostoop@hu.nl

Github: https://github.com/GidoStoop/Shared-Mobility-Location-Suitability-Model

Webmap:

https://webmap.hu.nl/en/app/location tool cargobike provu



North Sea



ShareDiMobiHub

Shared mobility: First national validated model for location selection of shared mobility vehicles

Based on workshops and a literature review, criteria were selected that can predict the potentially successful adoption of shared vehicles. Using these criteria, a location selection tool was developed that can predict where the potentially successful locations are. Each crossroad in the Netherlands has been evaluated with these criteria using open datasets. The goal of this tool is to gain and spread knowledge about the important criteria when selecting locations, as well as serving as a starting point for a data-driven discussion between service providers and policy makers.

The results shown in the example on this poster are based on user data for shared cargo bikes. However, efforts are currently being undertaken with service providers of shared moped, bicycles and cars to also validate and calibrate the model to these transport modes.

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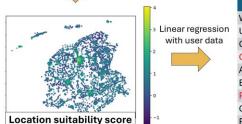








Calibrate model with weights based on coefficients



Combine layers

Walkability

Urbanization

Car ownership

Children in area

Education level

Public transport

Green ideals

Points of Interest

Indicator	Coefficient R ² = 0.50	P-value	Weights	
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